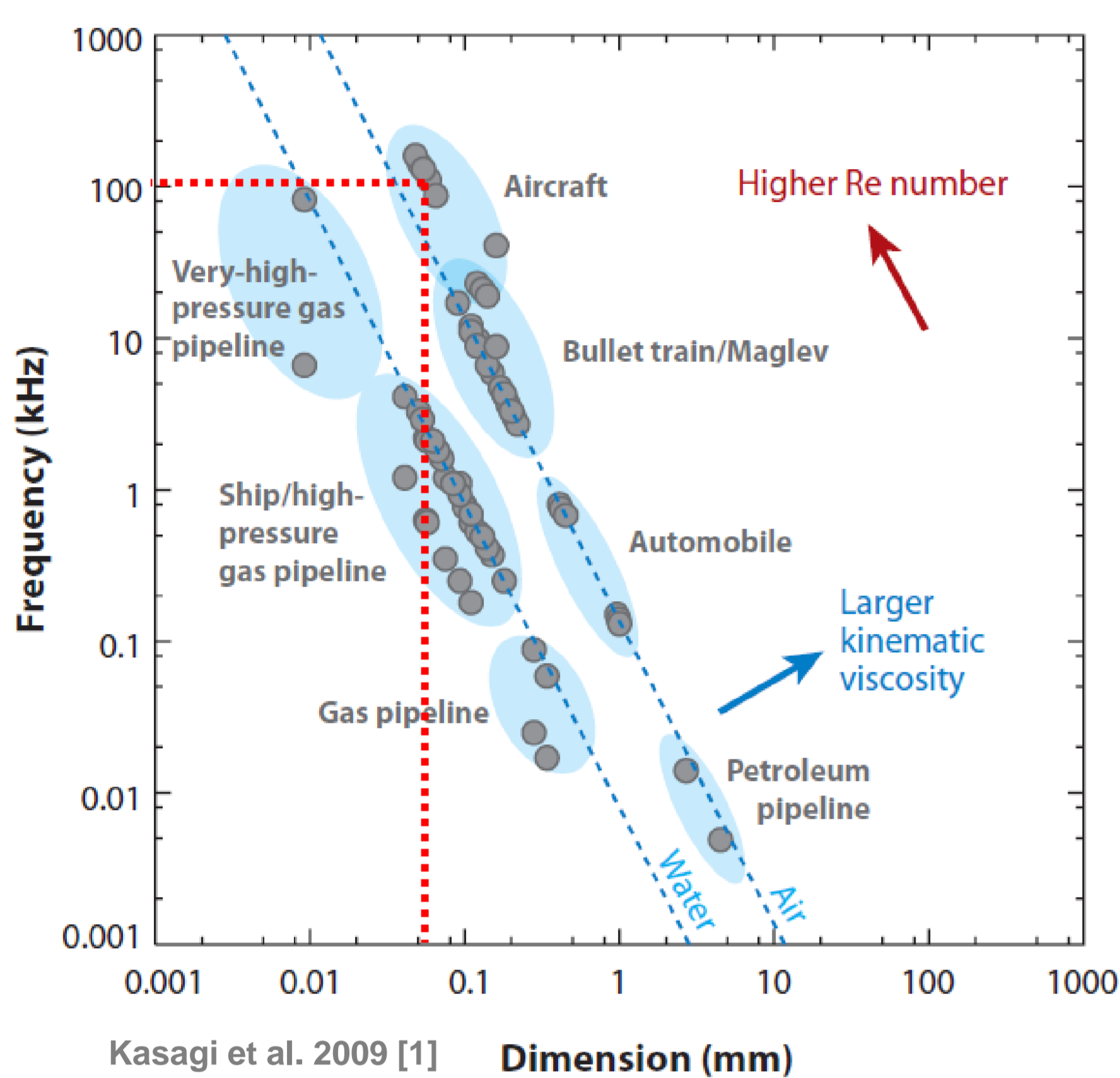
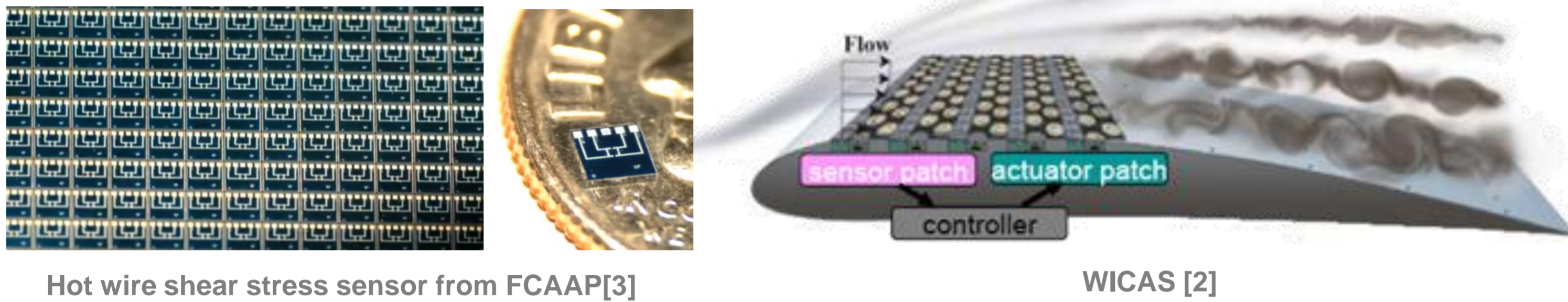


XDense: A Sensor Network for Extreme Dense Sensing

Motivation

Development of a sensor network architecture tailored for high sampling rate applications and high density of sensor node deployments

Application example: Active Flow Control (AFC)



Scales of **100 μm** for the sensor size and its interspacing

Sampling rates of **100 kHz** or more

Large number of sensors required for capturing the phenomena.

Preliminary Results and Future Work

The principle of operation is based in 3 different states:

1st Network Discovery

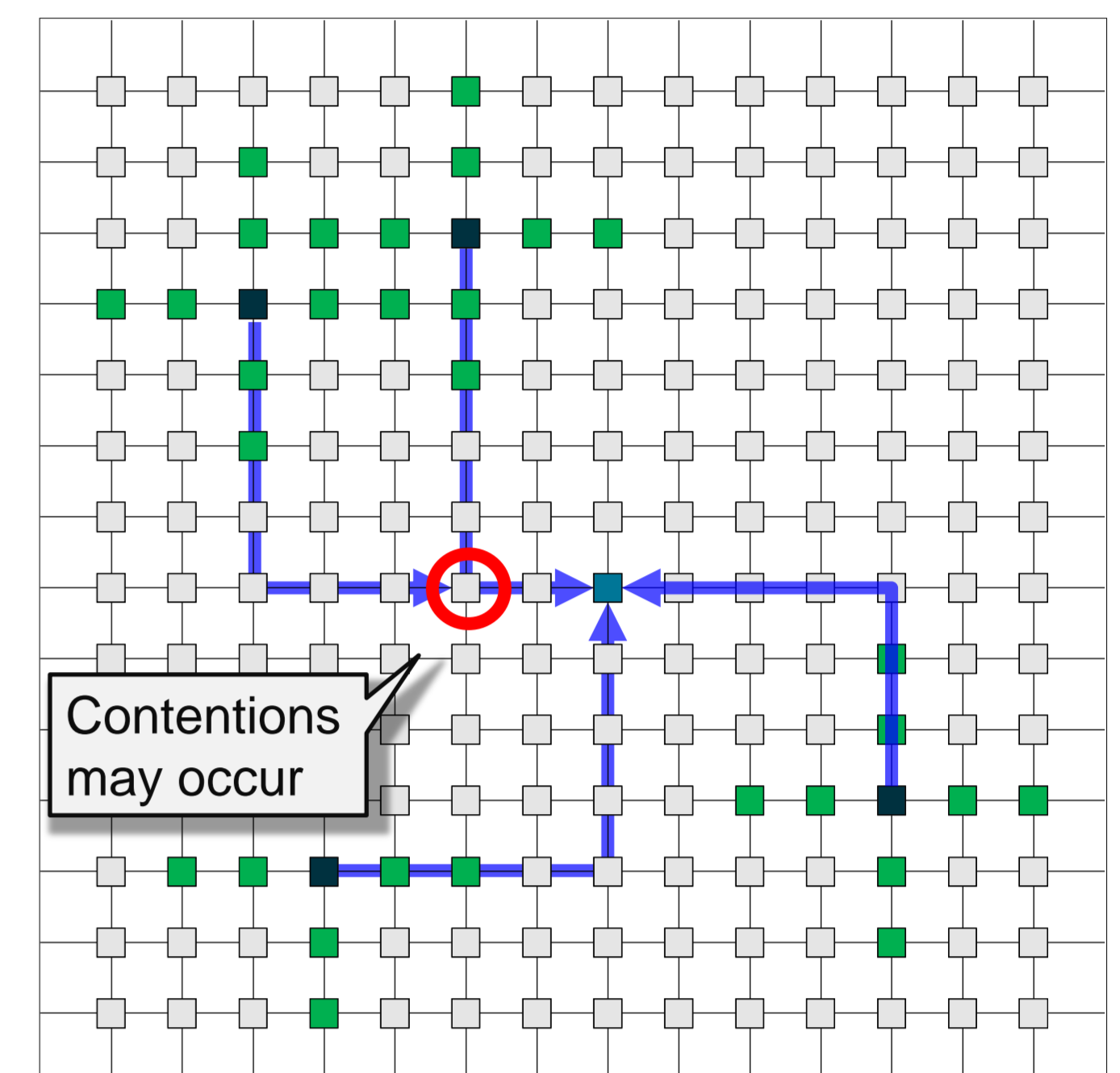
Each node discovers its neighbors and the closest path to the sink(s)

2nd Event Monitoring

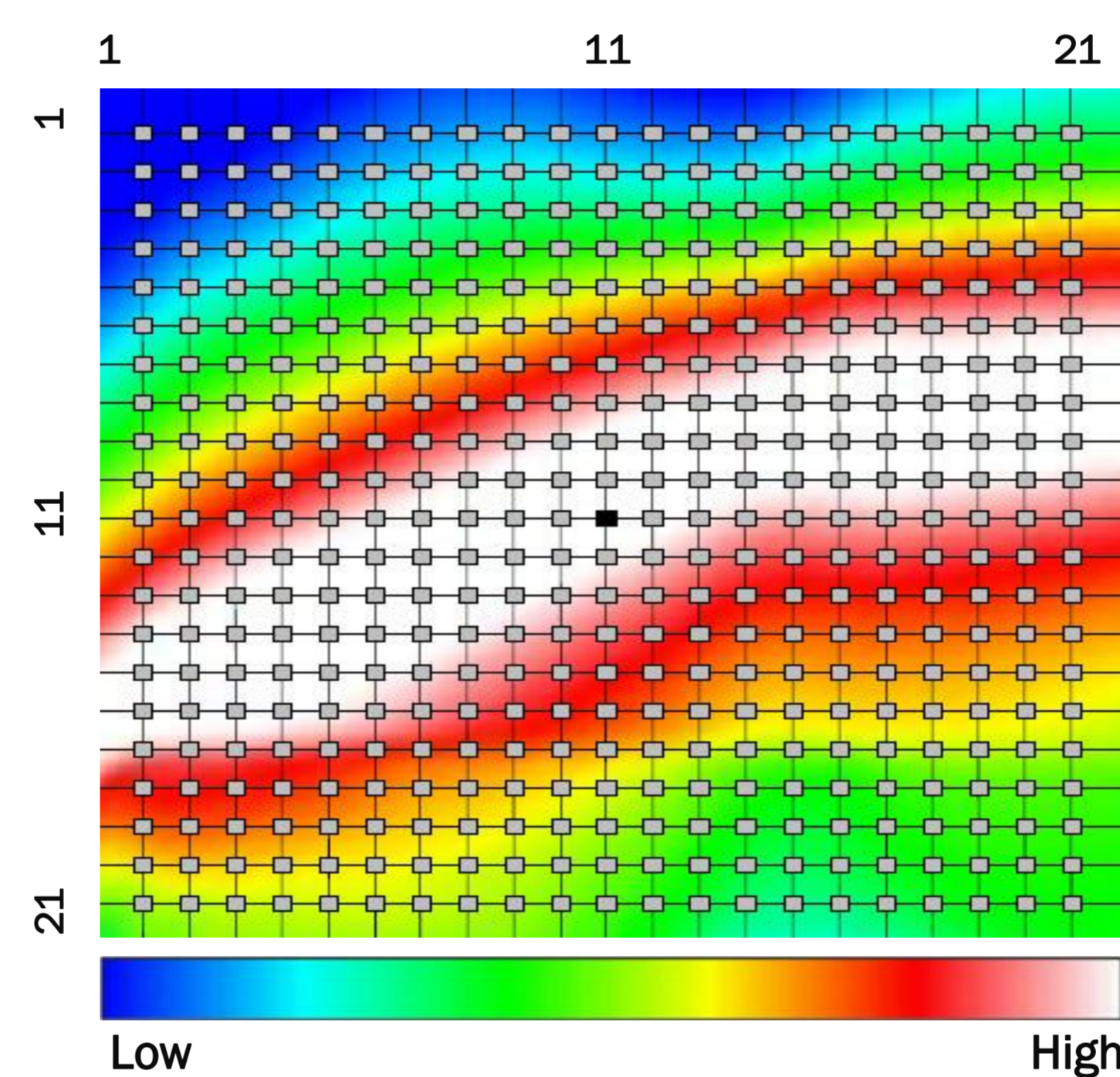
Sense the environment and communicate the values with their n-hops. (Ex: in figure $n = 2$)

3rd Event Announcement

A connection path to the sink is established and data is sent by the nodes who detected any event.



Simulation Scenario

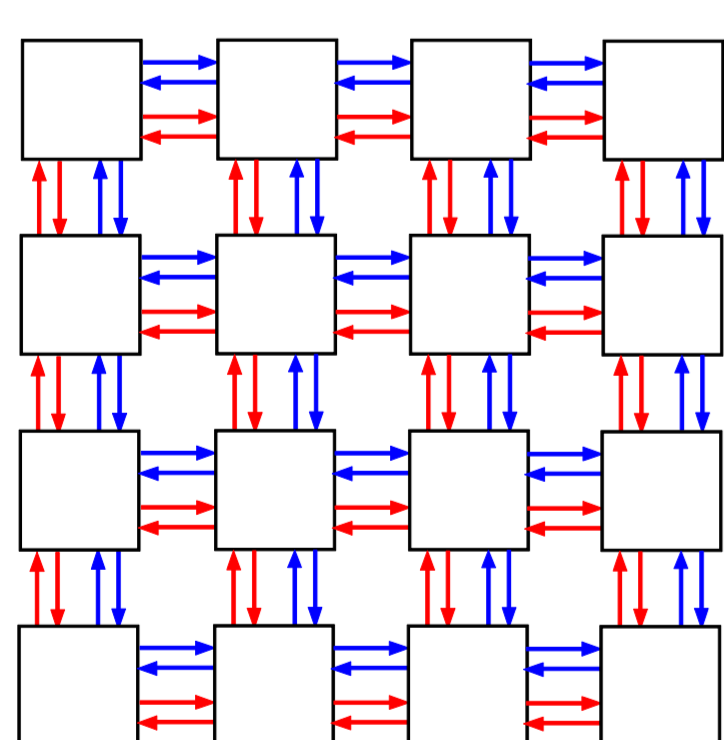


- Grid of 21 x 21 nodes, with one sink in center
- Grid is superimposed on a pressure distribution snapshot
- Neighborhood size is two ($n = 2$)
- ✓ Only 13% of the nodes transmitted
- ✓ Information enough to provide an accurate picture of phenomenon with low latency

Objectives and System Architecture

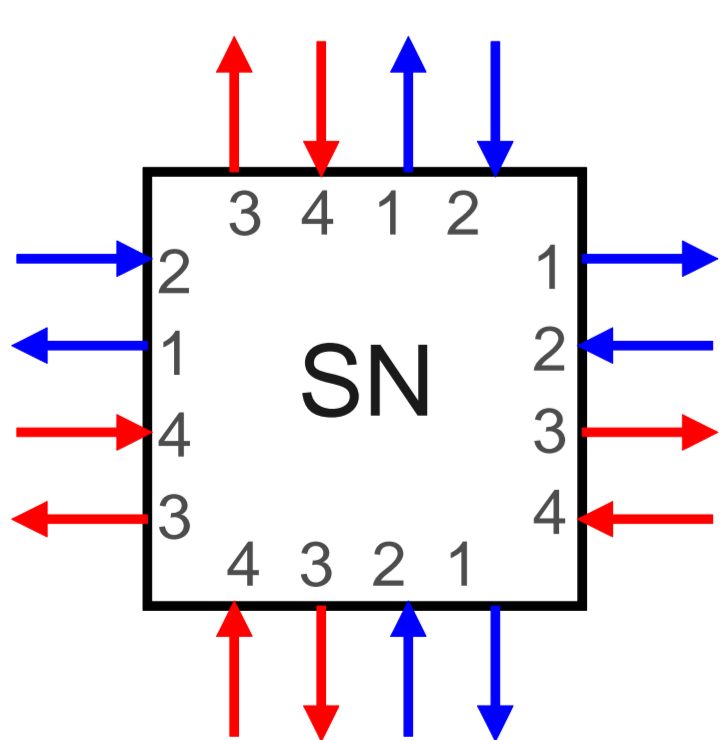
Objectives

- Investigate architectural and communication issues for a large-scale dense sensor network, addressing issues like network topology, medium access control, routing and in-network data processing.
- Design of distributed processing strategies for detecting events with low latency which is essential to meet the requirements of RT control systems.



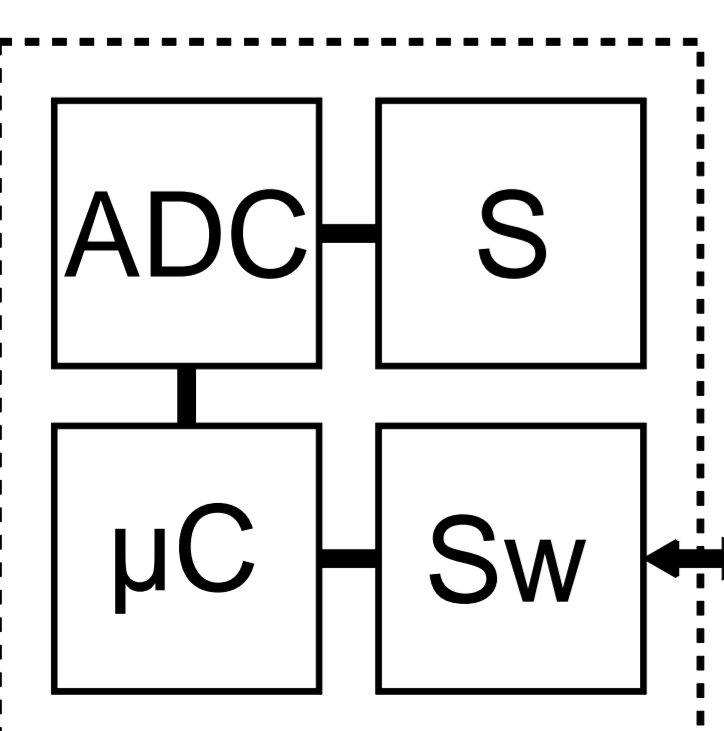
2D mesh sensor network:

- Distributed event detection, without the need of central data acquisition and processing;
- Regular structures resembles the architecture of a NoC.



Node Pinout:

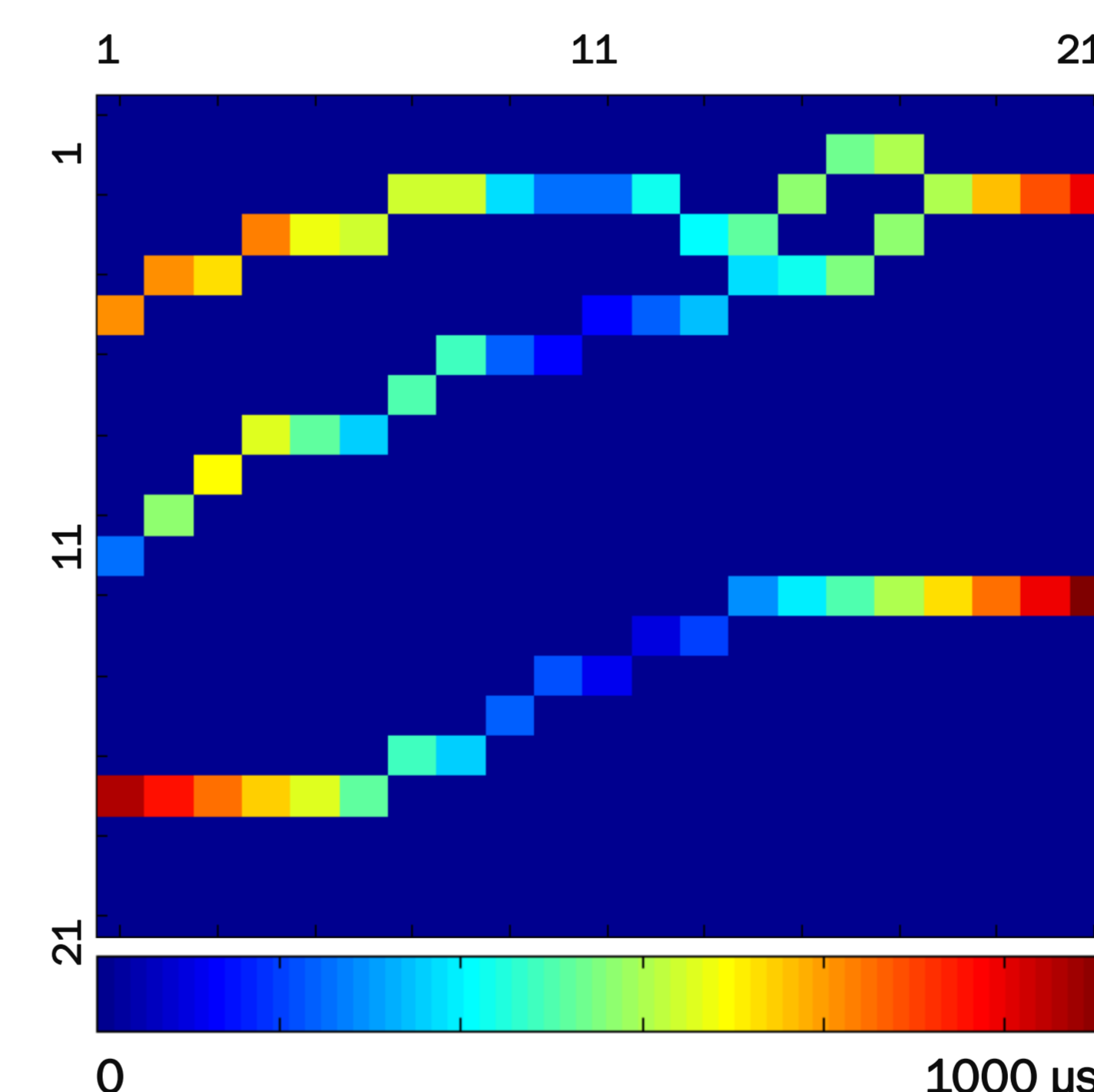
- Full duplex serial ports: input and output data pins
- Handshaking: input and output control pins



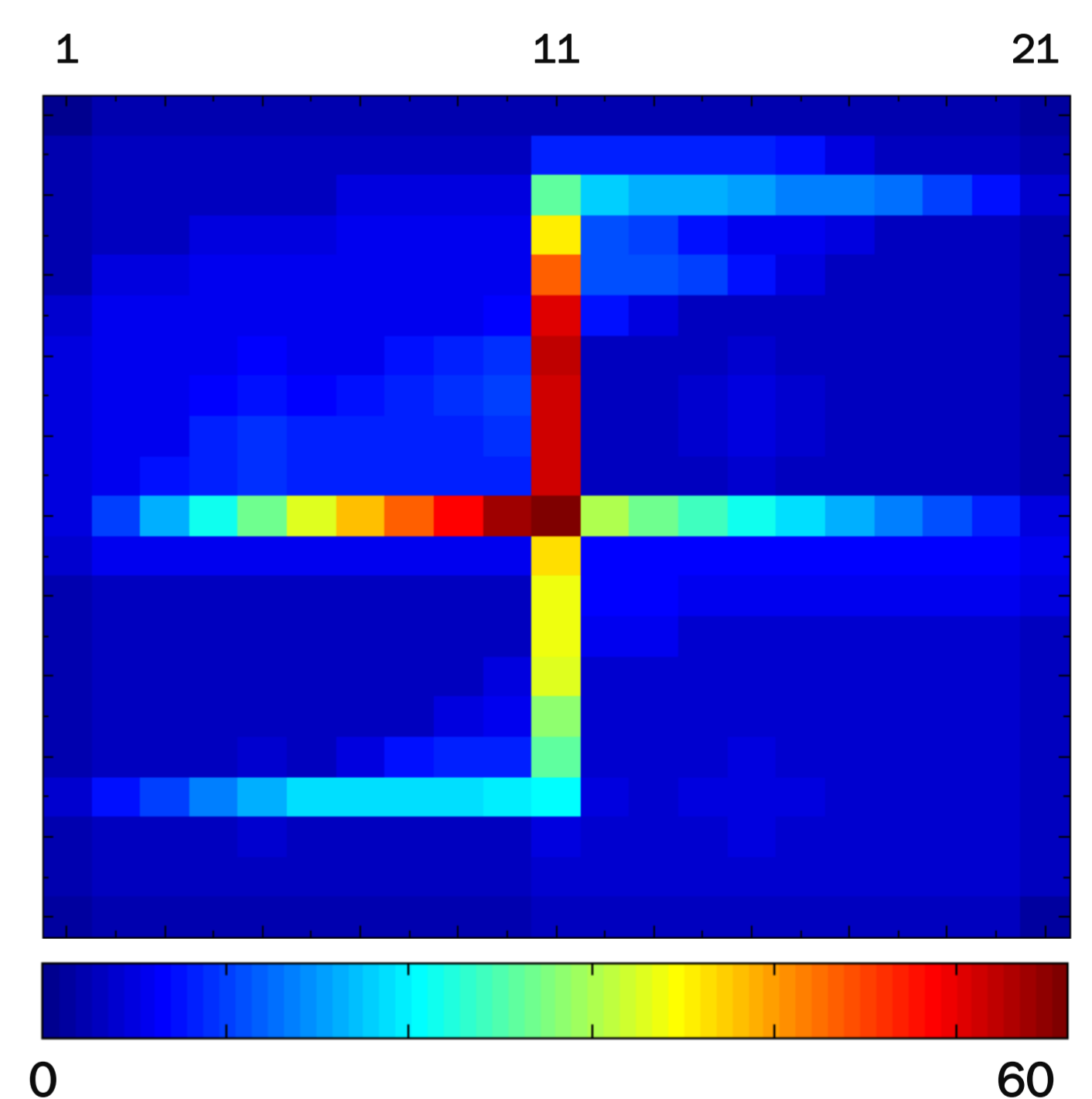
Node architecture

- Consists of one switch and one microcontroller connected to the sensor through one ADC.

Nodes Latency



Packets Transmitted per Node



Future Work

Examine the significance and efficacy of this approach by exploring aspects like routing, flow control and distributed data processing and aggregation.

References

- [1] Nobuhide Kasagi, Yuji Suzuki, and Koji Fukagata. Microelectromechanical systems-based feedback control of turbulence for skin friction reduction. Annual review of fluid mechanics, 41:231–251, 2009.
[2] Wireless Interconnectivity and Control of Active Systems Website (WICAS), <http://www.shef.ac.uk/systemsutc/projects/wicas>
[3] FCAAP. Florida Center for Advanced Aero-Propulsion

Projects:
FCOMP-01-0124-FEDER-037281 (CISTER);
FCOMP-01-0124-FEDER-020312 (SMARTSKIN);
FCOMP-01-0124-FEDER-012988 (SENODS);
FCOMP-01-0124-FEDER-028990 (PATTERN).
Co-financed by:

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